

Additive noise in discrete optimization

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Our acknowledgements to: A. Pruguel-Bennett, J.Rowe, J. Shapiro in Dagstuhl seminar Theory of Evolutionary Algorithms 2013, who participated in the discussions which initiated this work

Introduction

The problem

- Evolutionary Algorithm designed to optimize discrete functions
- What happens if we add *noise*?

Case 1

Gaussian noise

Case 2

Any noise with finite variance

Initial setting

Setting

Let:

- EA an Evolutionary Algorithm
- G_n an *instance*, i.e. a set of fitness functions from $\{0, 1\}^n$ to \mathbb{N} .
- Every $g \in G_n$ has an optimum $x^* := \arg \max g$

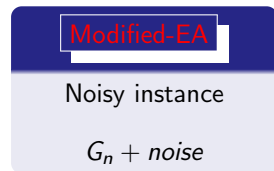
Definition (Complexity $f(n, \delta)$ of an algorithm EA)

The **complexity** $f(n, \delta)$ of an algorithm EA is the number of fitness evaluations needed to find the optimum of any function $g \in G_n$, with probability at least $1 - \delta$.

The Solution



Modify EA:
Revaluation individuals
Averaging their fitness



Revaluation-EA

Definition (Algorithm Revaluation-EA)

Let α and β two individuals. Then Revaluation-EA:

- To compute the fitness value of α :
Average between k fitness evaluations of α , where

$$k = \max \left(1, \left\lceil \sigma^2 \log \left(\frac{1 - \exp(\log(1 - \delta)/f(n, \delta))}{A} \right) / \log(B) \right\rceil \right)$$

- To compare the individual α and the individual β :
 - α better β if average of α greater by at least $\frac{1}{2}$
 - β better α if average of β greater by at least $\frac{1}{2}$
 - they have the same fitness value otherwise.

Theorem 1

Theorem

Assume that EA solves G_n with complexity $f(n, \delta)$. Then Revaluation-EA solves $G_n + \sigma\mathcal{N}$ with probability $(1 - \delta)^2$ and number of fitness evaluations

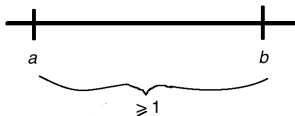
$$O\left(f(n, \delta) \left\lceil \sigma^2 \log\left(\frac{f(n, \delta)}{-\log(1 - \delta)}\right) \right\rceil\right) \quad (1)$$

Proof Theorem 1

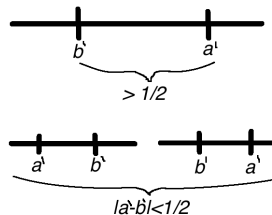
Step 1

Compute probability of “misranking” a *given* individual, using deviation of a Gaussian.

EA: $b > a$



Revaluation-EA: $b' \leq a'$



Proof Theorem 1

Step 1

Compute probability of “misranking” a *given* individual, using deviation of a Gaussian.

Step 2

Compute probability of misranking *any* individual, using union bound and Step 1.

Step 3

Compute probability of EA and Revaluation-EA having the same ranking
 \rightsquigarrow We have the result

ManyRevaluation-EA

Definition (Algorithm ManyRevaluation-EA)

Analogous to Revaluation-EA, but with:

$$k = \max(1, \lceil 4\sigma^2 f(n, \delta) / \delta \rceil) \quad (2)$$

Theorem 2

Theorem

Assume that EA solves G_n with complexity $f(n, \delta)$. Then ManyRevaluation-EA solves $G_n + \sigma N$ (with N some arbitrary noise with variance 1) with probability $(1 - \delta)^2$ and number of fitness evaluations

$$O\left(f(n, \delta) \max(1, 4\sigma^2 f(n, \delta)/\delta)\right). \quad (3)$$

Proof Theorem 2

Step 1

Compute probability of “misranking” a *given* individual, using **Chebyshev’s inequality**

Step 2

Compute probability of misranking *any* individual, using union bound and Step 1.

Step 3

Compute probability of EA and Revaluation-EA having the same ranking
~> We have the result

Application: OneMax

OneMax_n

For every $z \in \{0, 1\}^n$ we define:

$$\begin{aligned} \text{OM}_z : \{0, 1\}^n &\rightarrow \{0, \dots, n\} \\ x &\mapsto |\{j \in \{0, \dots, n\} \mid x_j = z_j\}| \end{aligned}$$

So, OneMax_n is the set of all $\text{OM}_z, z \in \{0, 1\}^n$

Algorithm and complexity

- $(1 + 1)$ -EA : $\Theta(n \log n)$

[Droste, Jansen, Wegener, 2002]

Conclusions

Contribution

From noise free case to noisy case modifying the original algorithm

- Find optimum with high probability
- Complexity of the algorithm for noisy instances

Influence of Noise

Gaussian

$$O\left(f(n, \delta) \left\lceil \sigma^2 \log \left(\frac{f(n, \delta)}{-\log(1-\delta)} \right) \right\rceil\right)$$

Any noise finite variance

$$O\left(f(n, \delta) \max\left(1, \frac{4\sigma^2 f(n, \delta)}{\delta}\right)\right)$$

Perspectives

Perspectives

- 1 Finding the complexity? Not free! [Oliveto, Witt, 2010]
- 2 Can we discard the need of the complexity *a priori*?
- 3 Reevaluate vs not reevaluate [Shapiro, Pruguel – Bennet, Rowe]
- 4 Complexity analysis in noisy settings