

Edwin Armstrong

1 Actuator and Sensor Coupling for Reconfigurable Robotic Systems

PhD thesis, 2000

From the abstract: This thesis discusses the need for techniques to implement real-time control capabilities within automated control systems, while maintaining the ability to easily modify, extend and reconfigure the system. We are specifically interested in automated control systems that utilise virtual sensors (a data and control abstraction of physical and other virtual sensors).

1.1 Publications

- [*Robot Control 2000 \(SYROCO'00\)*](#)

Ed teaches in the Department of Computer Science of the [University of Mary Hardin-Baylor](#) in Belton, Texas.